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BIG BANG- BIG CRUNCH BASED SATELLITE IMAGE CLASSIFICATION

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Abstract: Nature has always been a major source of inspiration to researchers. Nowadays researchers are working on the algorithms that are inspired by the nature. A number of algorithms are proposed which are based on inspiration from nature like Bio Geography based Optimization (BBO), Particle Swarm Optimization (PSO) etc. Recently a new nature inspired algorithm – Big Bang- Big Crunch (BBBC) has been proposed that relies on one of the theories of the evolution of the universe. In the Big Bang phase, particles are randomly spread into universe and in Big Crunch phase, randomly distributed particles are converged to a single point. Satellite image classification is an important task because it is the only way we can know about the land cover map of the inaccessible areas. Although a number of algorithms are proposed for satellite image classification, but there is always a search for alternative strategies which could be best suited for a particular land cover feature extraction task in hand. This paper is focused on classification of satellite image of a particular land cover using the theory of Big Bang- Big Crunch. The original BBBC optimization algorithm does not have the inbuilt property of classification which is required during image classification. Hence original algorithm has been adapted to classify the satellite image of a particular land cover. The results indicate that highly accurate land cover features can be extracted effectively when the proposed adaptations are used.

Keywords: Big-Bang Big Crunch, Bio Geography Based Optimization (BBO), Particle Swarm Optimization (PSO), satellite image classification

I. INTRODUCTION

A new nature inspired algorithm for optimization called Big Bang-Big Crunch (BBBC) optimization algorithm has been introduced recently by Osman K. Erol et. al. [1]. The algorithm is based upon the famous Big Bang- Big Crunch theory of evaluation of universe. The algorithm has been successfully applied to solve optimization problems in different areas like solving Optimal Power Flow Problems[6], Economic Dispatch with Valve-Point Effect[7], fuzzy rulebased generations from Numerical Data[8], Chaotic based BBBC for solving global optimization problems [9], multi criteria group decision making [10], damage detection [11]. For solving global optimization problems the BBBC algorithm has been shown to outperform the enhanced classical Genetic Algorithm for many Benchmark test functions [1]. Big Bang-Big Crunch algorithm is basically an optimization technique which is used to find optimized solution of a problem, but satellite image classification is a clustering problem that requires each pixel in the image to be classified in some class, hence adaptation in the original algorithm is undertaken and a new BBBC based satellite image classifier is developed.

A. Big Bang Crunch Theory

Big Bang- Big Crunch theory [15] [16] [17] is one of the famous and highly accepted theories of evaluation of universe. According to the Big Bang – Big Crunch theory, the universe began about twelve to fifteen billion years ago in a violent explosion. During the Big Bang phase, the most basic forces in nature were formed which were gravity and strong nuclear forces followed by the week nuclear and electromagnetic forces and particles like electrons, protons, neutrons, quarks etc were also formed. After the Big Bang Phase the nuclei of simple elements like hydrogen and helium were formed by nucleo-synthesis of protons and neutrons and matter came into existence by the nuclei bounding with the free electrons, and then galaxies and stars were formed by condensing of gases by

virtue of Gravity, this phase is known as Big Crunch Phase. So in the Big Bang Phase energy explosion produces randomness and disorder due to which particles are spread randomly whereas in Big Crunch phase the randomly distributed particles are drawn into an order and converged to an optimal point by gravitational attractions, nuclear forces etc. as shown in the figure 1.1 and 1.2.



Blast in Nature Random Spread of Particles

Figure 1.1: Big Bang Phase



Forces in Nature (Gravitational,Nuclear, Electomagnetics etc.) Convergence of Particles

Center of Mass

Figure. 1.2: Big- Crunch Phase

B. Satellite Image Classification

Satellite images are important and powerful tool to get information of land cover features of inaccessible remote areas. They provide qualitative and quantitative information and also reduce field work and time. These images have variety of uses, including: cartography, military intelligence and meteorology. Satellite image classification involves identification of different land cover classes on the image. Satellite image classification plays an important role in extracting and interpretation of important information from satellite images which could be required for variety purposes like - Spatial data mining [14], Extract information for an application, Thematic map creation, Field surveys, Effective decision making, Disaster management, studying various vegetation types like agriculture or forest, various land uses of urban area etc.

Rest of the paper is structured as follows - Section 2 depicts BBBC optimization algorithm. Section 3 contains the proposed work. Section 4 contains Result and Discussions and Section 5 contains Future work and References.

II. BB-BC OPTIMIZATION ALGORITHM

Big Bang-Big Crunch (BB-BC) optimization algorithm is used to find optimal solution of an objective function f(x). The algorithm has been divided into two phases (i) Big Bang (ii) Big Crunch.

In the Big-Bang phase particles are spread randomly in the space and in the Big-Crunch Phase randomly distributed particles are concentrated into one place known as center of mass which (CM) which is calculated according to the following equation:

$$CM = \frac{\sum_{i=0}^{i=N} \frac{x_i}{f(x_i)}}{\sum_{i=0}^{i=N} \frac{1}{f(x_i)}}$$
(1)

Where x_i is the ith particle in the D-Dimensional search space, $f(x_i)$ is the fitness value of the point x_i for the objective function f(x), N is the population size in the Big Bang Phase.

After the Big Crunch phase, Big Bang Phase follows in which the candidate solutions are again spread in the search space within the limits of the search space around the center of mass of the last phase for better convergence using the formula:

$$CM = CM + lr/j$$
(2)

Where 1 is the limit of the search space,

- r is the random number in [0,1]
- j is the iteration step

The described Big Bang – Big Crunch phase is continued till a termination criterion is met. The same is illustrated by the figure.2

Big Crunch Phase

Termination Criteria: Number of Iterations should be less than

Objective Function f(x): The function to be optimized.



Forces in nature (Gravitational, Nuclear, Electromagnetic etc.)

Explosion in nature

Random Spread

Convergence of particles

Center of Mass of particles

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CM = CM+lr/j
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Big Bang Phase

Figure 2: Big Bang-Big Cruch Optimization Algorithm

a fixed number.

III.

A. Pseudo Code of BBBC

Assumptions:

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Fitness $f(x_i)$: Value of Objective Function f(x) at a point x_i .

- Initialize the particles randomly in search space.
- > While the termination criteria is not met
 - Compute the center of mass of particles using eq.(1) (Big-Crunch Phase)
 - Compute the fitness of the center of mass.
 - Spread new particles around center of mass using eq.(2) (Big Bang Phase)
- ➢ End While
- Output CM as the solution of the objective function f(x)
- ➢ End

IV. PROPOSED WORK

A. Dataset Used

For the purpose of feature extraction a multi-spectral, multi resolution and multi-sensor 7-band satellite image of Alwar City (Rajasthan, India) of size 472 X 546 has been used.

These bands are Red, Green, Near Infra Red (NIR), Middle Infra Red (MIR), Radarsat –I (RS1), radarsat -2 (RS2) and Digiatl elevation Model (DEM) as shown in figure. 3(a-g).



The sample training data of each class as produced by the expert is shown in Figure.4. $2/3^{rd}$ of the training data has been used for development of the classifier based on BBBC optimization algorithm and $1/3^{rd}$ is used as validation/reference data.

	D2	-	() X 🗸	f _x					
	A	В	с	D	E	F	G	н	1
1									
2									
3									
4	х	Y	B1	B2	B3	B4	B5	B6	B7
5			RED	GRE	EN NIR	MIR	RS1	RS2	DEM
6									
7	287	265	91	83	128	93	86	64	15
8	288	267	101	83	129	102	93	40	15
9	290	253	89	78	117	89	91	186	15
10	290	264	87	82	122	98	51	143	15
11	291	251	115	101	135	111	142	110	15
12	292	256	109	94	135	98	44	144	15
13	292	268	101	88	131	100	79	17	15
14	293	260	107	94	137	104	101	129	15
15	293	321	125	106	170	142	36	25	15
16	294	247	89	83	122	102	117	188	15
17	295	245	140	128	157	118	83	12	15
18	295	251	136	127	146	120	220	110	15
19	295	255	105	96	124	98	110	77	15
20	295	264	101	88	135	100	44	76	15
21	296	251	130	122	148	117	137	113	15
22	296	252	128	120	149	113	72	126	15
23	296	260	103	90	122	98	67	39	15
24	297	243	134	115	162	117	46	111	15

Figure 4: Sample data for the classes produced by the expert.

B. Proposed Methodology

To classify a pixel in the satellite image known as Test Particle (TP) we have calculated the fitness of that pixel (TP) in all the classes in which it is to be classified. To calculate the fitness we have taken the objective function as the Euclidian distance of digital number of TP in each of the 7 bands from the digital number of Center of mass

For that we have used the proposed modified Big Bang-Big Crunch algorithm by using which we first have taken any 20 pixels of the training data of each class produced by the expert and calculated the Euclidian distance of each of those pixels in all the bands from the test particle (TP) and calculated the center of mass (CM). Next we calculated the fitness of the CM and compare with all the 20 particles and if any particle has less fitness than CM we made that particle CM. Then we again went to Big Bang phase and spread the particle around CM but within the limits of the search space using random number generators and calculate the fitness of the new particles and produced new center of mass. The process is repeated for certain number of times, 40 in our case as after 20-30 iterations we found that the fitness of the CM can't be further improved as shown by the graph in figure 5. After calculating the fitness of TP with each of the class we compare them to find the class in which the fitness is best and TP is assumed to belong to that class.

C. Proposed Algorithm

Algorithms: Big Bang –Big Crunch based satellite image classification

1. Get the multispectral satellite image.

2. Take the classes of the land cover (produced by the expert) – Water, Urban, Rocky, Barren and Vegetation having training pixels. Take the upper & lower bound of each class.

3. Take first N (N=20 in our case) training pixels of each class and consider them as first N particles in the universe.

4. Take any pixel from the image as a Test-Particle (TP) to be classified in any one of the classes given by the expert.

5. Repeat the following 40 times steps for each class - Water, Urban, Rocky, Barren and Vegetation to find fitness f1, f2, f3, f4& f5 of the test particle (TP) for each of the class respectively.

a) Calculate the fitness of each of the N training pixel/candidate solution based upon the Euclidean Distance of the pixel value of each band from the TP.

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b) Calculate the center of mass using the formula:

$$CM = \frac{\sum_{i=0}^{i=N} \frac{x_i}{f(x_i)}}{\sum_{i=0}^{i=N} \frac{1}{f(x_i)}}$$
⁽¹⁾

- c) Calculate the fitness of the center of mass (cmf)
- d) Compare the fitness of the center of mass (cmf) with each of the N candidate solutions. If any particle has less fitness as center of mass, make that particle center of mass.
- e) Spread the particles again around the center of mass within the bounds to get new N candidate solutions using formula

$$CM+l*r/j \tag{2}$$

Where l is the bounds, r is random number and j is the iteration step.

6. Compare each of the fitness f1, f2, f3, f4 & f5. Absorb the

test particle in the class having least fitness.

7. Take another point from the image as TP and go to step 5 until all the particles are classified.

8. END



Figure 5: Variation of Fitness with No. of Iterations

V. RESULTS AND DISCUSSIONS

After applying the proposed algorithm on the 7-band of Alwar image the classified image is obtained with different classes like vegetation, water, rocky, urban and barren. The different colors define the different terrain features in this image. The Green color represents vegetation region, Blue color represents water region, Red color represents rocky region, Yellow color represents urban region & Magenta color represents barren region respectively. This classified image can be compared with the original satellite image as shown in figure 6.



Figure 6(a-b): Comparison of (a) Original Alwar image and



Figure 6(b): Classified image.

A. Accuracy Assessment

To determine the accuracy of the proposed algorithm we have to find accuracy in the image classification. The aim is to quantitatively determine how effectively the pixels were grouped into correct feature classes in the area under investigation. Classification accuracy of our proposed algorithm is expressed using classification error matrix [2]. Error matrices compare, on a category by category basis, the relationship between known reference data/validation data (ground truth) and the corresponding results of an automated classification. A set of randomly selected reference pixels is used for experimentation. Reference pixels are points on the classified image for which actual features are known. For the purpose of validation we have taken 150 vegetation pixels, 190 Urban pixels, 200 Rocky pixels, 70 water pixels and 80 barren land pixels from the training set and the error matrix obtained is shown below. The error matrix interpretation along column suggests how many pixels are classified correctly by the algorithm. For e.g. in the forth column, out of 190 Urban pixels, 181 pixels were classified correctly into Urban by the proposed algorithm, 6 were misclassified as Barren, 2 as vegetation and 1 as rocky.

Feature	Rocky	Water	Barren	Urban	Vegetation	Total
Rocky	127	0	8	1	0	136
Water	70	70	0	0	0	140
Barren	3	0	66	6	0	75
Urban	0	0	6	181	0	187
Vegetation	0	0	0	2	150	152
Total	200	70	80	190	150	690

Table 1: Error Matrix of BBBC

Various factors that can be considered for the accuracy assessments are explained with their calculated values as follows:

Kappa Coefficient: The kappa coefficient is used to interpret the results of error matrix. It is a discrete multivariate technique. The Kappa statistics incorporates the observations on the diagonal as well as the off diagonal which gives more robust assessment of accuracy than other accuracy measures. The Kappa coefficient of the Alwar image can be calculated by applying following formula to the Error Matrix:

$$\mathbf{K} = \frac{\mathbf{N}\sum_{i=1}^{r} x_{ii} - \sum_{i=1}^{r} (x_{i+}, x_{+i})}{N^2 - \sum_{i=1}^{r} (x_{i+}, x_{+i})}$$

r = Number of rows in the error matrix (r =5 in our case)

 x_{ii} = the number of observations in row i and column i (on the major diagonal)

 x_{i+} = the total number of observations in row i (shown as marginal total to right of the matrix)

 x_{+i} = the total number of observations in column i (shown as marginal total at the bottom of the matrix)

N = Total numbers of observations included in the matrix (N = 690 in our case)

The Kappa (K) coefficient of the Alwar image is 0.8233 which indicates that an observed classification is 82.33 % better than one resulting from chance.

Producer's Accuracy: Producer's accuracy measures that how much of the land in each class was classified correctly. In other words it indicates that how much the image is classified correctly category wise by the analyst. It is calculated as:

 $\alpha = \frac{ \text{No. of correctly classified pixels} }{ \text{Total No. of training set pixels} } \\ \text{used for that category (the column total)} }$

Producer's accuracy of the proposed BBBC based classifier is shown in Table 2.

User's accuracy: User's accuracy measures how well the classification performed in the field by category (rows). It is calculated as:

 $\beta = \frac{\text{No. of correctly classified pixels}}{\text{Total No. of pixels used}}$ $\beta = \frac{\text{In each category (on major diagonal)}}{\text{Total No. of pixels used}}$

User's accuracy of the proposed BBBC based classifier is shown in Table 2.

Table 2: Different Accuracy	Measures	For	Alwar	Image
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Accuracy	Features (%)					
	Vegetation	Urban	Rocky	Water	Open	
Producer's Accuracy	100	96.79	93.38	100	88	
User's Accuracy	100	95.26	63.5	100	82.5	

Based upon the Producer's Accuracy and User's Accuracy from Table 2 we find that Big Bang- Big Crunch based classifier gives 100% result for Vegetation & water and 95.26% result for Urban area as depicted by Figure. 7. So we can say that the algorithm has tendency towards vegetation, water and urban area.



Figure 7: Tendency of BBBC classifier for different Terrain Features

Overall Accuracy: Overall accuracy is measure of the number of correct observations divided by the total number of classifications. This is very crude measure of accuracy and is calculated as below:

$$\gamma = \frac{\text{(Sum of all values on major diagonal)}}{\text{Total No. of classifications}}$$

The overall accuracy of the proposed BBBC based classifier is 0.86.

B. Comparison with other nature inspired algorithms

The results are compared with other nature inspired algorithms like Biogeography based Optimization (BBO) [18], Particle Swarm Optimization (PSO) [4], Hybrid Rough Set & Biogeography Based optimization [19], Hybrid Biogeography Based optimization & Flower Pollination by Artificial bees [12], Hybrid Fuzzy System & Biogeography Based optimization [19], Hybrid Ant Colony optimization & Self Organising Feature Map [13] and Hybrid Ant Colony Optimization & Biogeography Based optimization [19]. For this we have taken the three parameters:

1) Error Matrices: We have taken the Error matrices for different nature inspired algorithms for comparison purposes which is represented by Table 3 -9.

Table 3: Error Matrix of BBO [18]

Feature	Rocky	Water	Barren	Urban	Vegetatio	Total
					n	
Rocky	175	0	3	15	0	194
Water	0	70	0	0	0	70
Barren	26	0	128	81	21	256
Urban	0	0	39	92	1	129
Vegetati on	1	0	0	1	127	129
Total	202	70	170	189	150	781

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Feature	Rocky	Water	Barren	Urban	Vegetati	Total
					on	
Rocky	286	0	0	3	18	307
Water	0	59	0	0	28	87
Barren	0	0	24	7	1	32
Urban	0	0	7	22	4	33
Vegetatio n	0	47	0	0	79	126
Total	286	106	31	32	130	585

Table 4: Error Matrix attained of PSO [4]

Table 5: Error Matrix of Hybrid Rough/BBO [19]

Feature	Rocky	Water	Barren	Urban	Vegetation	Total
Rocky	176	1	17	2	6	202
Water	3	69	0	0	0	72
Barren	20	0	119	91	17	247
Urban	1	0	32	88	0	121
Vegetation	0	0	2	9	127	138
Total	200	70	170	190	150	780

Table 6: Error Matrix of Hybrid FPAB/BBO [12]

Feature	Rocky	Water	Barren	Urban	Vegetation	Total
Rocky	181	0	28	0	10	219
Water	0	70	0	0	0	70
Barren	17	0	105	89	2	213
Urban	2	0	36	90	0	128
Vegetation	0	0	1	11	138	150
Total	200	70	170	190	150	780

Feature	Rocky	Water	Barren	Urban	Vegetat	Total
					ion	
Rocky	173	0	3	15	0	192
Water	0	70	0	0	0	70
Barren	26	0	128	81	21	255
Urban	0	0	39	93	1	130
Vegetation	1	0	0	1	127	129
Total	200	70	170	190	150	780

Table 7: Error Matrix of Hybrid Fuzzy/BBO [19]

Feature	Rocky	Water	Barren	Urban	Vegeta tion	Total
Rocky	161	0	5	0	6	172
Water	2	65	1	1	0	69
Barren	11	0	110	46	0	167
Urban	21	0	47	121	0	189
Vegetation	5	5	7	22	144	183
Total	200	70	170	190	150	780

Table 9: Error Matrix of Hybrid ACO/BBO [19]

	Rock	Water	Barren	Urban	Vegetatio	Total
Feature	у				n	
Rocky	168	0	10	2	2	182
Water	1	70	1	0	3	75
Barren	27	0	125	27	0	179
Urban	0	0	26	127	0	153
Vegetati on	4	0	8	34	145	191
Total	200	70	170	190	150	780

Comparison of different terrain features of different nature inspired algorithms based upon the error matrices is represented by the figure 8.



Figure 8: Comparison of Different Terrain Features Identification by different nature inspired algorithms

This indicates that BBBC optimization gives better performance for Rocky, Urban, Vegetation and water.

2) *Kappa Coefficient:* The value of the Kappa coefficient for the proposed algorithm is 0.8233 which shows that the proposed classification is better as the Kappa coefficient of some other algorithms are as shown in Fig.9.



Figure 9: Comparison of Kappa Coefficient of Different Nature Inspired Algorithms

Kappa coefficient of Biogeography based Optimization (BBO) [18] is 0.69, Particle Swarm Optimization (PSO) [4] is 0.70, Hybrid Rough Set & Biogeography Based optimization [19] is 0.67, Hybrid Biogeography Based optimization & Flower Pollination by Artificial bees [12] is 0.68, Hybrid Fuzzy System & Biogeography Based optimization [19] is 0.69, Hybrid Ant Colony optimization & Self Organising Feature Map [13] is 0.70 and Hybrid Ant Colony Optimization & Biogeography Based optimization [19] is 0.76 as illustrated by Fig 9.

3) Overall Accuracy: The overall accuracy for satellite image classification for the proposed algorism is 0.86 which shows that the observed classification is better as the value of overall accuracy of BBO, PSO, Hybrid Rough/BBO, Hybrid FPBAB/BBO, Hybrid Fuzzy/BBO, Hybrid ACO/SOFM, Hybrid ACO/BBO are 0.76, 0.80, 0.74, 0.75,0.76, 0.77, 0.81, respectively as illustrated by Figure 10.



Figure 10: Comparison of Overall Accuracy of different nature inspired algorithms

VI. CONCLUSION AND FUTURE WORK

In this paper we have used Big Bang- Big Crunch algorithm as an efficient land cover classifier for satellite image. The results produced by the algorithm are highly significant which indicates that the BBBC is an efficient classification tool for satellite image

The future scope of the algorithm is that it can be hybrid with other nature inspired technique or implemented with different random number generator functions like Lèvy distribution for spreading the particle in the space, so that Kappa coefficient can be further improved. Also the results suggest that BBBC algorithm proved to be an efficient algorithm and can also be applied effectively in other areas of research like medical imaging etc

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